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adjusting a discontinuous component in a frequency domain of a first pixel of the plurality of pixels located at the block boundary based on a corresponding component in the frequency domain of a second pixel of the plurality of pixels near the block boundary; and

applying the adjusting operation to a spatial domain of the first pixel to reduce a blocking artifact]

defining pixels, S_0 , S_1 , and S_2 centering around a block boundary;

obtaining a mode determination value to selectively determine a deblocking

mode as a default mode or a DC offset mode in accordance with a degree of the blocking

artifact;

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obtaining frequency information of the surroundings of the block boundary for each pixel, using a 4-point kernel, if the default mode is determined;

adjusting a magnitude of a discontinuous component, belonging to the block boundary, to the minimum value of a magnitude of a discontinuous component, belonging to the surrounding of the block boundary, in a frequency domain, and applying said adjusting operation to a spatial domain; and

motion, such as a setting, if the DC offset mode is determined.

- 2. (Amended) The method according to claim 1, wherein the [selecting] the default obtaining through [applying] adjusting steps are performed in a first mode.
- 3. (Amended) The method according to claim 1, wherein a magnitude of the discontinuous component in the [first] \underline{S}_0 pixel is adjusted to a magnitude of the corresponding component in [the] \underline{a} second pixel, wherein the magnitude of the corresponding component in the second pixel is based on a smallest value of corresponding component magnitudes in [remaining] the \underline{S}_1 and \underline{S}_2 pixels [of the plurality of pixels].

4. (Amended) The method according to claim 3, wherein the adjusting step satisfies at least one of the following conditions:

$$v_{3}' = v_{3} - d;$$
 and

$$\begin{aligned} v_4{'} &= v_4 + d; \text{ where } d = \text{CLIP } (c_2(a_{3,0}{'} - a_{3,0}) // c_3, 0, (v_3 - v_4) / 2)^* \delta(\big|a_{3,0}\big| \big\langle \text{QP}), \\ a_{3,0}{'} &= \text{SIGN}(a_{3,0})^* \text{MIN}(\big|a_{3,0}\big|, \big|a_{3,1}\big|, \big|a_{3,2}\big|), \text{ wherein } v_3 - v_4 + d_3, v_4 + d_3, v_5 + d_4, v_5 + d_4, v_6 + d_4, v_7 + d_5, v_8 + d_5, v_8 + d_6, v_8 + d_8, v$$

 v_4 are initial boundary pixel values, v_3' - v_4' are adjusted boundary pixel values, $a_{3,0}$ - $a_{3,2}$ are the discontinuous component of the discrete cosine transform coefficients of the [first

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and second] S_0 , S_1 and S_2 pixels, C_2 and C_3 are DCT kernel coefficients and QP is a quantization parameter of a macroblock containing V_4 .

- 5. (Amended) The method according to claim 3, wherein the [remaining] \underline{S}_1 and \underline{S}_2 pixels [of the plurality of pixels] are positioned within a block adjacent the block boundary.
- 6. (Amended) The method according to claim 1, further comprising:

 determining a smoothness level of the plurality of pixels; and

 selecting one of [a first and a second] the default mode and the DC offset

 mode based on the smoothness level, wherein the blocking artifact is reduced based on the
 selected mode.
- 7. (Amended) The method according to claim 6, wherein the [second] \overline{DC} offset mode is selected when the following condition is satisfied: $(v_0 = = v_1 \& \& v_1 = = v_2 \& \& v_2 = = v_3 \& \& v_4 = = v_5 \& \& v_5 = = v_6 \& \& v_6 = = v_7)$, wherein $v_0 v_7$ are boundary pixel values.

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8. (Amended) The method according to claim 6, wherein in the [second] <u>DC</u> offset mode is selected for a region of the motion picture where there is little motion.

10. (Amended) The method according to claim 6, wherein the adjusting step in DC offset

the [second] default mode satisfies at least one of the following conditions:

$$v_{3}' = v_{3} - d;$$

$$v_4' = v_4 + d;$$

$$v_2' = v_2 - d_2;$$

$$v_5' = v_5 + d_2;$$

$$v_1' = v_1 - d_3$$
; and

$${v_6}' = v_6 + d_3, \text{ where } d_1 = (3(v_3 - v_4)//8)*\delta(\left| \, a_{3,0} \right| \big< QP),$$

$$d_2 = (3(v_3 - v_4)//16) * \delta(|a_{3,0}| \langle QP), and$$

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$$d_3 = (3(v_3 - v_4)//32)*\delta(|a_{3,0}| \langle QP), \text{ wherein } v_0 - v_7 \text{ are}$$

initial boundary pixel values, $v_1' - v_6'$ are adjusted boundary pixel values, $a_{3,0}$ is the discontinuous component of the discrete cosine transform coefficients of [the] a first pixel belonging at the block boundary and QP is a quantization parameter of a macroblock containing v_4 .